## Comment on "Non-Hermitian Quantum Mechanics with Minimal Length Uncertainty"\*

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**Abstract.** We demonstrate that the recent paper by Jana and Roy entitled "Non-Hermitian quantum mechanics with minimal length uncertainty" [SIGMA 5 (2009), 083, 7 pages, arXiv:0908.1755] contains various misconceptions. We compare with an analysis on the same topic carried out previously in our manuscript [arXiv:0907.5354]. In particular, we show that the metric operators computed for the deformed non-Hermitian Swanson models differs in both cases and is inconsistent in the former.

 $Key\ words:$  non-Hermitian Hamiltonians; deformed canonical commutation relations; minimal length

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It is known for some time that the deformations of the standard canonical commutation relations between the position operator P and the momentum operator X will inevitably lead to a minimal length, that is a bound beyond which the localization of space-time events are no longer possible. In a recent manuscript [1] we investigated various limits of the q-deformationed relations

$$[X,P] = i\hbar q^{f(N)}(\alpha\delta + \beta\gamma) + \frac{i\hbar(q^2 - 1)}{\alpha\delta + \beta\gamma} \left(\delta\gamma X^2 + \alpha\beta P^2 + i\alpha\delta XP - i\beta\gamma PX\right),$$

in conjunction with the constraint  $4\alpha\gamma=(q^2+1)$ , with  $\alpha,\beta,\gamma,\delta\in\mathbb{R}$  and f being an arbitrary function of the number operator N. One may consider various types of Hamiltonian systems, either Hermitian or non-Hermitian, and replace the original standard canonical variables  $(x_0,p_0)$ , obeying  $[x_0,p_0]=i\hbar$ , by (X,P). It is crucial to note that even when the undeformed Hamiltonian is Hermitian  $H(x_0,p_0)=H^{\dagger}(x_0,p_0)$  the deformed Hamiltonian is inevitably non-Hermitian  $H(X,P)\neq H^{\dagger}(X,P)$  as a consequence of the fact that X and/or P are no longer Hermitian. Of course one may also deform Hamiltonians, which are already non-Hermitian when undeformed  $H(x_0,p_0)\neq H^{\dagger}(x_0,p_0)$ . In both cases a proper quantum mechanical description requires the re-definition of the metric to compensate for the introduction of non-Hermitian variables and in the latter an additional change due to the fact that the Hamiltonian was non-Hermitian in the first place.

In a certain limit, as specified in [1], X and P allow for a well-known representation of the form  $X = (1+\tau p_0^2)x_0$  and  $P = p_0$ , which in momentum space, i.e.  $x_0 = i\hbar\partial_{p_0}$ , corresponds to the one used by Jana and Roy [2], up to an irrelevant additional term  $i\hbar\tilde{\gamma}P$ . (Whenever constants with the same name but different meanings occur in [2] and [1] we dress the former with a tilde.)

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The additional term can simply be gauged away and has no physical significance. Jana and Roy have studied the non-Hermitian displaced harmonic oscillator and the Swanson model. As we have previously also investigated the latter in [1], we shall comment on the differences. The conventions in [2] are

$$H_{\rm JR}(a,a^{\dagger}) = \omega a^{\dagger} a + \lambda a^2 + \tilde{\delta}(a^{\dagger})^2 + \frac{\omega}{2}$$

with  $\lambda \neq \tilde{\delta} \in \mathbb{R}$  and  $a = (P - i\omega X)/\sqrt{2m\hbar\omega}$ ,  $a^{\dagger} = (P + i\omega X)/\sqrt{2m\hbar\omega}$ , whereas in [1] we used

$$H_{\rm BF}(X,P) = \frac{P^2}{2m} + \frac{m\omega^2}{2}X^2 + i\mu\{X,P\}$$

with  $\mu \in \mathbb{R}$  as a starting point. Setting  $\hbar = m = 1$  it is easy to see that the models coincide when  $\lambda = -\tilde{\delta}$  and  $\mu = \tilde{\delta} - \lambda$ . The Hamiltonians exhibit a "twofold" non-Hermiticity, one resulting from the fact that when  $\lambda \neq \tilde{\delta}$  even the undeformed Hamiltonian is non-Hermitian and the other resulting from the replacement of the Hermitian variables  $(x_0, p_0)$  by (X, P). The factor of the metric operator to compensate for the non-Hermiticity of X coincides in both cases, but the factor which is required due to the non-Hermitian nature of the undeformed case differs in both cases

$$\rho_{\rm BF} = e^{2\mu P^2}$$
 and  $\rho_{\rm JR} = (1 + \tau P^2)^{\frac{\mu}{\omega^2 \tau}}.$ 

We have made the above identifications such that  $H_{\rm JR}(a,a^\dagger)=H_{\rm BF}(X,P)$  and replaced the deformation parameter  $\beta$  used in [2] by  $\tau$  employed in [1]. It is well known that when given only a non-Hermitian Hamiltonian, the metric operator can not be uniquely determined. However, as argued in [1] with the specification of the observable X, which coincides in [2] and [1], the outcome is unique and we can therefore directly compare  $\rho_{\rm BF}$  and  $\rho_{\rm JR}$ . The limit  $\tau \to 0$  reduces the deformed Hamiltonian  $H_{\rm JR}=H_{\rm BF}$  to the standard Swanson Hamiltonian, such that  $\rho_{\rm JR}$  and  $\rho_{\rm BF}$  should acquire the form of a previously constructed metric operator. This is indeed the case for  $\rho_{\rm BF}$ , but not for  $\rho_{\rm JR}$ . In fact it is unclear how to carry out this limit for  $\rho_{\rm JR}$  and we therefore conclude that the metric  $\rho_{\rm JR}$  is incorrect.

## References

- [1] Bagchi B., Fring A., Minimal length in quantum mechanics and non-Hermitian Hamiltonian systems, arXiv:0907.5354.
- [2] Jana T.K., Roy P., Non-Hermitian quantum mechanics with minimal length uncertainty, SIGMA 5 (2009), 083, 7 pages, arXiv:0908.1755.